



Simrad CS90

Fish-finding sonar

Software Release Note

24.7.1

This document describes the changes introduced with the new software version.

- **Product:** CS90
- **Software version:** 24.7.1
- **Upgrade from version:** 23.9.2/24.7.0

This software controls all functionality in the CS90 system. This includes transmission and reception, interfaces with external peripherals and sensors, and all user interface.

A firmware update for the Transceiver Unit is not included with this release.

Additional end-user documents related to the CS90 system can be found on our website. This includes publications that are translated into other languages. Selected publications are also provided in IETM (*Interactive Electronic Technical Manual*) formats.

- <https://www.kongsberg.com/cs90>

SIMRAD
By KONGSBERG

Document information

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Warning

The equipment to which this manual applies must only be used for the purpose for which it was designed. Improper use or maintenance may cause damage to the equipment and/or injury to personnel. You must be familiar with the contents of the appropriate manuals before attempting to operate or work on the equipment.

Kongsberg Discovery disclaims any responsibility for damage or injury caused by improper installation, use or maintenance of the equipment.

Disclaimer

Kongsberg Discovery AS endeavours to ensure that all information in this document is correct and fairly stated, but does not accept liability for any errors or omissions.

Support information

If you require maintenance or repair, contact your local dealer. You can also contact us using the following address: simrad.support@simrad.com. If you need information about our other products, visit <https://www.kongsberg.com/simrad>. On this website you will also find a list of our dealers and distributors.

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Software changes

Marker

If you operate your sonar system with a traditional computer mouse, you can now press the scroll wheel to place a marker on the sonar presentation.

QuadPing™

We have now implemented the *QuadPing™* presentation mode.

☛ [QuadPing™](#) on page 14

New functionality added to the **Tilt** function

☛ [Tilt function](#) on page 15

Link Horizontal Pings

This is an "on/off" switch. Activate **Link Horizontal Pings** to "connect" all the horizontal transmissions to each other. When the beams are linked, they tilt together but do not necessarily use the same angle. The distance between each beam is fixed, and defined by the value you have chosen for **Beam Spacing**.

Beam Spacing

Select a value for **Beam Spacing** to define the distance (in degrees) between the linked beams.

New functionality added to the **Motion Reference Unit** page

You can now choose from several Motion Reference Unit sources.

☛ [Motion Reference Unit page](#) on page 18

Hull unit indicator

The hull unit indicator on the top bar flashes when the hull unit is being hoisted or lowered.

New functionality added to the Operating Panels

- Added *Horizontal 3* range as an option for the rotary switch.

- Added option *Place Marker* for push-down rotation switch (Mk2 and Mk3 operating panels)
 - Added option *Delete All Objects* to push-down rotation switch (Mk3) and push buttons for Mk2.
 - Added option *Increase Display Gain* and *Decrease Display Gain* for push buttons (Mk2 and Mk3 operating panels).
 - Added option *Display Gain* for rotary switches (Mk2 and Mk3 operating panels).
- ☛ [Operating Panel page](#) on page 22

Coverage plot

We have added a coverage plot to the **Vertical 2** ping in the *Horizontal* view.

Do I need to upgrade?

We recommend that all users update their software.

This software update introduces new functionality. It also addresses software bugs that have been reported by our users, or detected during our own product testing.

Software licenses

The CS90 system does not need any software licenses to operate. However, specific software license codes "unlocks" additional functionality.

The software license is a 32 character hexadecimal string based on the hardware identifier (**Hardware ID**). This unique identifier is generated using information from key components in the Processor Unit. The software license is linked to the physical Processor Unit. You cannot move the CS90 system software from one Processor Unit to another unless you also request and install a new license.

In order to obtain a software license you must contact one of our dealers or distributors. You can also use the request form on our website, or contact our support department directly.

Software installation

Note



You must remove the old version of the software before you install the new version.

A dedicated wizard is used to install the software. Installation of additional operating system components may be required. These are installed automatically. Observe the information offered in the wizard.

Registered dealers and distributors can download the new software version from our website.

Topics

[Removing the operating software, page 9](#)

[Installing a new version of the operating software, page 11](#)

Removing the operating software

Before you can install the new software version, you must remove the old version.

Before you begin

The following items may be useful:




- Computer mouse
- Computer keyboard

Neither tools nor instruments are required. This procedure is made for the Microsoft® Windows® 10 operating system. It is assumed that you are familiar with this operating system.

About this task

Removal of the software is done using functionality provided by the operating system.

Procedure

- 1 Turn on the Processor Unit.
- 2 Select **Power off** to turn off the system.
- 3 In the **Power Off** dialog box, select **Exit to Operating System** to close the CS90 program. 
- 4 If applicable: Connect the keyboard and the mouse to USB sockets on the Processor Unit.
- 5 Uninstall the application.
 - a If applicable: Open the on-screen keyboard.
 - b In the bottom left corner of your desktop, select the looking glass to start a search.
 - c Type Control Panel to locate the application, then open it. 
 - d Select **Programs and Features**. 
 - e On the list provided, locate the software you shall uninstall.
 - f Select it, then select **Uninstall**.
 - g Observe the **Remove existing settings** dialog box.
 - h Do not select any check boxes!
 - i Select **Uninstall** in the dialog box to remove the software.
 - j Follow the instructions provided by the wizard.
- 6 Click the [X] in the top right corner to close the Control Panel.
- 7 If applicable: Disconnect the keyboard and the mouse from the Processor Unit.

Installing a new version of the operating software

A dedicated wizard is used to install the software. The operating software for the CS90 system must be downloaded on a separate computer.

Before you begin

The following specific items are required for this task:

- Personal computer
- USB flash drive
- Computer mouse (Optional)
- Computer keyboard (Optional)

Neither tools nor instruments are required. This procedure is made for the Microsoft® Windows® 10 operating system. It is assumed that you are familiar with this operating system.

Procedure

- 1 On the personal computer:
 - a Download the new software version.
 - b Unpack the ZIP file to access the executable application file.
 - c Copy the application file to a USB flash drive.
- 2 Turn on the Processor Unit.
- 3 Make the following preparations.
 - a If applicable: Connect the keyboard and the mouse to USB sockets on the Processor Unit.
 - b Insert the USB flash drive.
- 4 Install the new version of the application.
 - a From the Windows® **Start** button, right-click to open File Explorer.
 - b Locate the executable setup file (.exe).
 - c Copy the file to a temporary folder on the "D" drive.
 - d Double-click the setup executable file to start the installation.
 - e Select the check box to accept the license terms and conditions.
 - f Select **Install**.
 - g Follow the instructions provided by the wizard.

We recommend that you install the software in the default folder suggested by the wizard.

- h Close File Explorer.
 - i Remove the USB flash drive.
- 5 On the Processor Unit desktop, double-click the CS90 icon to start the program.
 - 6 If applicable: Disconnect the keyboard and the mouse from the Processor Unit.

End-user documentation

The end-user documentation for the CS90 system has been updated with this software release.

The CS90 **Reference Manual** is included with the CS90 software as context sensitive on-line help.

Additional end-user documents related to the CS90 system can be found on our website. This includes publications that are translated into other languages. Selected publications are also provided in IETM (*Interactive Electronic Technical Manual*) formats.

- www.kongsberg.com/cs90

Updated functions and dialog boxes

Topics

[QuadPing™, page 14](#)

[Tilt function, page 15](#)

[Motion Reference Unit page, page 18](#)

[Operating Panel page, page 22](#)

QuadPing™

Simrad has introduced a groundbreaking commercial- and sportfishing tool called the *QuadPing™*. QuadPing is an advanced sonar functionality that uses four transmissions ("pings") simultaneously to find and track the fish from deep in the water to your vessel. We have implemented the functionality as a dedicated presentation mode on the CS90 system.

The QuadPing™ functionality is a free upgrade for all current users of our high-frequency sonars, making these the only sonars with such advanced features.

QuadPing is a significant step forward in sonar technology. It provides you with a real advantage. QuadPing sends out four "pings" simultaneously in dual, split-screen mode. The echoes from the first ping are shown in the first view as a reference. The echoes from the other three pings, each with a different tilt angle, are displayed in the second view. The first view detects the fish, while the second view maps and tracks the catch all the way to your boat. The sonar's full omni-stabilization of transmission and reception beams enables this functionality. This functionality is particularly beneficial for purse seiners and sports fishing.

Key features:

- Two horizontal views: one single swath of echoes in the left view and three swaths combined into one view on the right hand side.
- The three combined pings are separated by 10 degrees tilt. The tilt of the middle ping is shown.
- The frequency is shown for the second swath. The other two are ± 1 kHz of the second swath.
- Other settings, such as range and bandwidth, apply to all three swaths.

Tilt function

The **Tilt** function allows you to control the vertical angle of the sonar beams.

Specifications: Tilt

- **Horizontal views:** $-10 - +60$ degrees
- **Vertical views:** $0 - +90$ degrees
- **Plane view:** $-10 - +90$ degrees
- **Inspection views:** $-10 - +60$ degrees

**How to open**

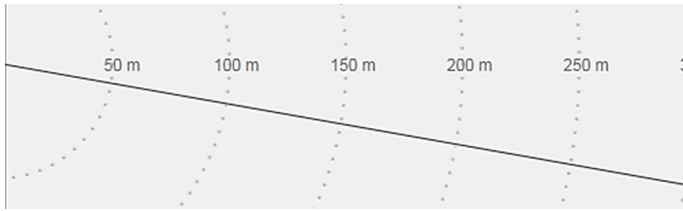
Open this function from the **Main** menu.

Description

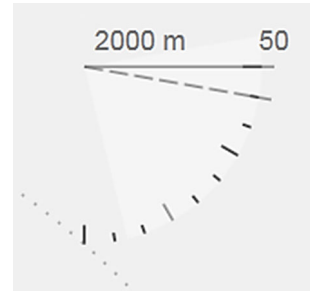
The transmitted sonar beams can be tilted electronically. The following methods can be used to adjust this setting:

- Select either side of the button to choose a value.
- Select the middle of the button and keep the mouse button pressed. Drag the cursor sideways to increase or decrease the value. Release the mouse button when requested value is shown.
- In a *Vertical* view, click on the tilt line, keep the mouse button depressed, and drag the line up or down.


The current tilt is shown with a solid line in the *Vertical* views.




In the *Horizontal* views, the current settings for range, gain and tilt are shown in the top left corner of the view. When you change the tilt a dotted line presents the requested tilt while the solid line presents the actual tilt.



Note

 *The tilt setting is only valid for currently selected (active) view. The tilt limits depend on the opening angle of the vertical beam. This means that you may not always be permitted to select the maximum specified tilt limits.*

Tip

 *With the various beams provided by the CS90 system, it may be difficult to understand the concepts. How do these beams "behave" in the water? By means of a graphic presentation, the **Beam Visualization** dialog box attempts to give you a better understanding of how the acoustic beams are transmitted into the water. Open the **Beam Visualization** dialog box from the **Setup** menu.*

Details

Tilt

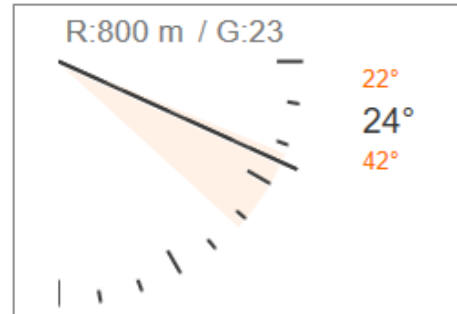
The following methods can be used to adjust this setting:

- Select either side of the button to choose a value.
- Select the middle of the button and keep the mouse button pressed. Drag the cursor sideways to increase or decrease the value. Release the mouse button when requested value is shown.
- Select the middle of the button to open it. If you have a keyboard connected to the CS90 system, type the requested value.

Auto

This is an "on/off" function. When *Auto Tilt* mode is activated the beam will automatically change its tilt angle for each transmission ("ping").

The centre of the tilt sector is defined by the chosen tilt angle just before the *Auto Tilt* mode is started. The chosen tilt sector is shown on the tilt indicator in the *Horizontal* view using a shaded background.



Select **Step** to set the size (in degrees) of each tilt step.

Select **Sector** to set the size (in degrees) of the vertical tilt sector.

Tip



The *Mk2 Operating Panel* is fitted with three function buttons. The buttons are identified as F1, F2 and F3. One of these buttons can be assigned to activate the *Auto Tilt* mode. The **Operating Panel** page is used to select which physical hardware panel you use, and to assign functionality to the programmable buttons. This page is located in the **Installation** dialog box.

Step

Select **Step** to set the size of each tilt step (in degrees) in *Auto Tilt* mode.

Select either side of the button to choose a value. Select the middle of the button to open it. If you have a keyboard connected to the CS90 system, type the requested value.

Sector

Select **Sector** to set the size (in degrees) of the vertical tilt sector in *Auto Tilt* mode.

Select either side of the button to choose a value. Select the middle of the button to open it. If you have a keyboard connected to the CS90 system, type the requested value.

Link Inspection Beams

This is an "on/off" switch. Activate **Link Inspection Beams** to "connect" all the inspection beams together. Select **Apply to All** use the chosen setting in all the *Inspection* views. When the beams are linked, they are tilted simultaneously. The distance between each beam is fixed, and defined by the value you have chosen for **Beam Spacing**.

You can link the inspection beams for both vertical and horizontal movements. You can not link both tilt and bearing at the same time.

Beam Spacing

Select a value for **Beam Spacing** to define the distance (in degrees) between the linked beams.

Link Horizontal Pings

This is an "on/off" switch. Activate **Link Horizontal Pings** to "connect" all the horizontal transmissions to each other. When the beams are linked, they tilt together but do not necessarily use the same angle. The distance between each beam is fixed, and defined by the value you have chosen for **Beam Spacing**.

Beam Spacing

Select a value for **Beam Spacing** to define the distance (in degrees) between the linked beams.

Apply to All

Check this box if you wish to use the chosen setting in all the *Inspection* views.

Related functionality

Operating Panel

The Mk1 Operating Panel offers separate **Tilt** buttons to control the vertical angle of the sonar beams.. *(The Mk1 Operating Panel is no longer provided with new sonars. This information is provided for legacy reasons.)*

The Mk2 Operating Panel is fitted with three rotary switches. The Mk3 Operating Panel is fitted with two rotary switches. The switches are identified with numbers. Each switch can be assigned a function related to range, gain, bearing or tilt. The **Operating Panel** page is used to assign functionality to the programmable buttons. This page is located in the **Installation** dialog box.

Microsoft Xbox Controller

This function can also be controlled from a Microsoft Xbox Controller connected to the Processor Unit.

Motion Reference Unit page

The motion reference unit (MRU) measures the roll and pitch movements of the vessel. Some sensor models also measure heave. The information provided by the motion sensor is used by the CS90 system to stabilize the beams.

How to open

This page is located in the **Installation** dialog box. To open the page, select **Installation** on the **Setup** menu.



Prerequisites

The **Installation** dialog box is not available when your CS90 system is set to *Replay* mode.

Description

The CS90 system is provided with a built-in motion sensor to provide electronic stabilization of the sonar beams. It is placed inside the Motor Control Unit. For improved operational accuracy, an external motion reference unit (MRU) can be used.

- External: Use the **Motion Reference Unit** page to define the data format and the communication port used to import motion information from an external sensor.
- Internal: Use the internal sensor.

The external sensor must be connected using a serial communication line. If you don't have any available COM ports you must first release one on the **I/O Setup** page. Make sure that you do not put the same COM port to other use on the **I/O Setup** page.

Tip



If the sensor is malfunctioning the input can be disabled.

- Select **None** to disconnect the CS90 system from both external and internal motion sensors.
- The **Stabilization** function allows you to enable or disable the input from the motion sensor. This function is opened from the **Setup** menu.

Details

Source

Select *Internal* to use the built-in motion sensor. Select *External* to use a third-party motion sensor.

Sensor

- External: Select the datagram you want to use
- Internal: Select the sensor you want to use.

Motion Reference Unit

Source:

Sensor:

Protocol:

Interface:

COM Port:

Baud Rate:

Select **None** to disconnect the CS90 system from both external and internal motion sensors.


The following options are available:

- **EM3000 LAN:** This is the default setting. The Hull Unit Control board processes the sensor data.
- **Hull Unit Control:** This is the recommended setting. The Hull Unit Control board provides unprocessed sensor data. The sensor data processing takes place in the Processor Unit.

The Hull Unit Control board is located in the lower right corner of the Motor Control Unit. Its primary purposes are:

- It controls the transducer's hoisting and lowering operations and provides their status.
- It reads the built-in motion sensor output and promptly transmits this crucial data to the Transceiver Unit.
- It receives error reports from the hull unit sensors and sends these to the Processor Unit to generate a message.

Note

 *You can only select unprocessed sensor data if the Hull Unit Control board software supports this feature. The software version must be 1.3.5 or later. Use the **Hull Unit** page to read the software and firmware versions from the Hull Unit Control board.*

Protocol

This text reflects the chosen datagram format. The term *datagram* has been defined as follows:

A self-contained, independent entity of data carrying sufficient information to be routed from the source to the destination computer without reliance on earlier exchanges between this source and destination computer and the transporting network.

<https://tools.ietf.org/html/rfc1594>, April 2016

Interface

This text reflects the interface format you are using.

COM Port

This setting is only available if you use a serial line to interface your sensor. Select **COMx** to connect to the external motion sensor. "COMx" is the serial port to which the motion sensor is connected.

Baud Rate

This setting is only available if you use a serial line to interface your sensor. Use this setting to specify the baud rate ("speed") for the serial communication.

LAN Port

This setting is only available if you use the local area network (LAN) to interface your sensor. The text identifies the local area network (LAN) port in use on the remote device. The information is provided for reference purposes. You can not change this information.

IP Address

This setting is only available if you use the local area network (LAN) to interface your sensor. The text identifies the IP Address in use on the remote device. The information is provided for reference purposes. You can not change this information.

Status

The current status of the sensor communication is shown. "Not connected" means that the input from the sensor is missing. A message like this (example) verifies that the CS90 system is connected to the built-in motion sensor:

Connected to 192.168.1.30 CS90 Beamformer

Related functionality

Stabilization

The **Stabilization** function allows you to enable or disable the input from the motion sensor. If you disable the input from the sensor, the beams will not be compensated for pitch and roll movements. This function is opened from the **Setup** menu.

Hull Unit

Use the **Hull Unit** page to read the software and firmware versions from the Hull Unit Control board. This page is located in the **Diagnostics** dialog box.

Operating Panel page

The Operating Panel offers all necessary control functions for normal operation. It further allows you to assign certain functions to dedicated buttons and switches. The **Operating Panel** page is used to select which physical hardware panel you use, and to assign functionality to the programmable buttons.

How to open

This page is located in the **Installation** dialog box. To open the page, select **Installation** on the **Setup** menu.



Prerequisites

The **Installation** dialog box is not available when your CS90 system is set to *Replay* mode.

Description

The controls provided by the operating panel are arranged in logical functional groups. This arrangement offers you straightforward operation with fast access to all relevant functionality. All the functionality the CS90 system provides can be accessed using the trackball on the operating panel and the menu system shown in the display presentation.

The CS90 system supports several different operating panels. These are referred to as "MkX" where "X" is an integer.

- The Mk1 Operating Panel is connected to the Processor Unit with three cables. The dual interface cable provides power and serial communication. The USB interface cable is used to read the trackball movements. The Processor Unit must be fitted with a custom made interface board. A small commercial power supply is used to provide power to the Operating Panel. (The Mk1 Operating Panel is no longer provided with new sonars. This information is provided for legacy reasons.)
- The Mk2 Operating Panel is connected to the Processor Unit using an Ethernet cable. The Operating Panel is provided with a built-in power supply.
- The Mk3 Operating Panel is connected to the Processor Unit with a USB cable. A dedicated power supply unit is not required. This is a compact operating panel that takes up less space.

The Mk2 Operating Panel is the standard panel provided for the CS90 system.

Select which operating panel to use. Assign functionality as permitted by each type of operating panel.

Topics

[Operating Panel Mk1, page 23](#)

[Operating Panel Mk2, page 24](#)

[Operating Panel Mk3, page 29](#)

Operating Panel Mk1

The Mk1 Operating Panel is connected to the Processor Unit with three cables. The dual interface cable provides power and serial communication. The USB interface cable is used to read the trackball movements. A small commercial power supply is used to provide power to the Operating Panel.

Details

User Setting Buttons

On the Mk3 Operating Panel, the requested user setting or presentation mode is chosen with a single button. Select **Mode Selection** to specify what you want to use the buttons for. Assign one predefined user setting *or* presentation mode to each button on the Operating Panel.

Tip



*Before you can assign custom user settings to the operating panel, a selection of settings must be available from the **User Settings** dialog box. The **User Settings** dialog box is located on the **Main** menu.*

Communication

This functionality is only applicable for the Mk1 Operating Panel. The Mk1 Operating Panel is connected to the Processor Unit with three cables. The dual interface cable provides power and serial communication. The USB interface cable is used to read the trackball movements.


Primary Port

Choose which serial line communication port you wish to use to communicate with the Operating Panel.

Secondary Port

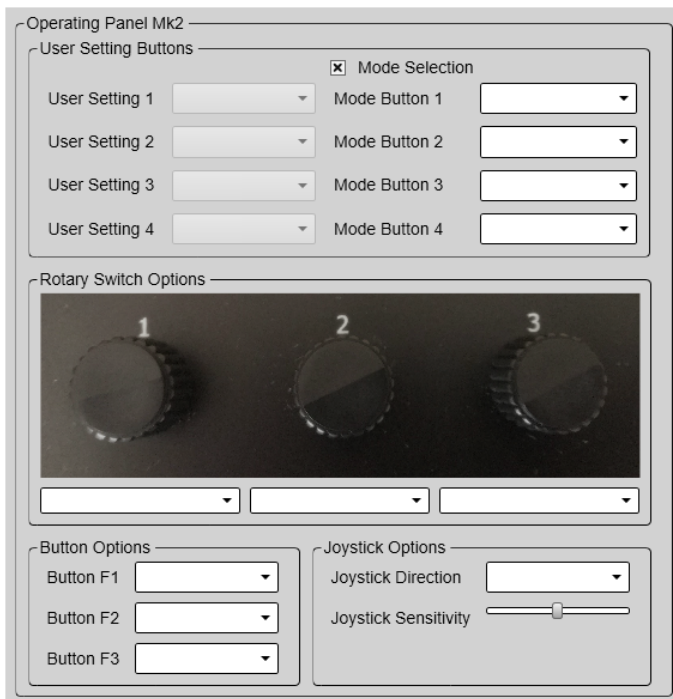
If you only use one Operating Panel, set this choice to *None*.

Note

 *It is very important that the chosen communication port is not put to other use in the **I/O Setup** page in the **Installation** dialog box. If you have two operating panels in use, neither communication ports must be used for any other purposes.*

Operating Panel Mk2

The Mk2 Operating Panel is connected to the Processor Unit using an Ethernet cable. The Operating Panel is provided with a built-in power supply.



Details

User Settings / Presentation Modes

On the Mk2 Operating Panel, the four buttons dedicated for user settings or presentation modes are located the top of the panel. Select **Mode Selection** to specify what you want to use the buttons for. Assign one predefined user setting *or* presentation mode to each button on the Operating Panel.



Tip



*Before you can assign custom user settings to the operating panel, a selection of settings must be available from the **User Settings** dialog box. The **User Settings** dialog box is located on the **Main** menu.*

*Any user setting selected on the Operating Panel is identified in the upper left corner of the Horizontal view. The identifying number refers to the **User Setting** number on the **Operating Panel** page. Click on the text to make it larger. Click one more time to restore the original font size.*

Rotary Switch Options

The Mk2 Operating Panel is fitted with three rotary switches. The switches are identified with numbers. Each switch can be assigned a function related to range, gain, bearing or tilt.

Under **Rotary Switch Options**, assign one function to each rotary switch on the Operating Panel. The following functions can be assigned:

Horizontal Range

This is the range setting in the *Horizontal* view.

Horizontal Range 2

This is the range setting in the *second Horizontal* view when a "dual" presentation mode is used.

Horizontal Range 3

This is the range setting in the *third Horizontal* view when the *QuadPing™* presentation mode is used.

Vertical Range

This is the range setting in the *Vertical* view.

Vertical Range 2

This is the range setting in the *second Vertical* view when a "dual" presentation mode is used.

Inspection Range

This is the range setting in the *Inspection* view.

Plane Range

This is the range setting in the *Plane* view.

Active Ping Range

This is the range setting in the currently active view.

Active Ping Gain

This is the gain setting in the currently active view

Active Ping Bearing

This is the bearing setting in the currently active view.

Active Ping Tilt

This is the tilt setting in the currently active view

Display Gain

Use this setting together with **Gain** to adjust the sensitivity of the CS90 system. **Display Gain** controls the "amount" of echo that is displayed, in other words the "strength" or "intensity" of the echo presentation. The function thus increases or decreases the presentation of the echo colours.

The gain is increased and decreased in steps of 1 dB. The chosen display gain will automatically apply to all the beams.

You can also control this functionality from the **Display** menu.

Button Options

The Mk2 Operating Panel is fitted with three function buttons. The buttons are identified as F1, F2 and F3. Each button can be assigned a dedicated function. The three function buttons are grouped with the Screen Capture button.

Under **Button Options**, assign one function to each Fx button on the Operating Panel. The following functions can be assigned:

None

No specific functionality is assigned.

Auto Tilt

This is an "on/off" function. When *Auto Tilt* mode is activated the beam will automatically change its tilt angle for each transmission ("ping"). The centre of the tilt sector is defined by the chosen tilt angle just before the *Auto Tilt* mode is started. The chosen tilt sector is shown on the tilt indicator in the *Horizontal* view



using a shaded background. The sector and step settings are made using the **Tilt** function on the **Main** menu.

Zoom

Place the cursor anywhere in the view, right-click and select **Zoom**. Only one zoom level is provided. Select **Zoom** one more time to restore the original view.

Menu Off

This is an "on/off" function. Unless you need to make frequent changes to the operating parameters, you may want to hide the menu from the display presentation. This gives you more space for echo information.

Own Ship

This is the same function as **Place Own Ship Marker** on the shortcut menu. Select this function to add a square symbol to the vessel's current position in the echo presentation. The own ship marker is now regarded as an *object*. All information about the object is shown in the **Objects** menu listed as "OSM". Use **Delete Own Ship Marker** on the shortcut menu to delete the marker from the current view.

Auto Bearing

This is an "on/off" function. Set this function to *On* to start the automatic search function. In the *Auto Bearing* mode the CS90 system will automatically search within defined sector limits. The sector is identified in the view using two angular symbols. The sector and step settings are made using the **Bearing** function on the **Main** menu.

Screen Recording

This is an "on/off" function. The **Screen Recording** function allows you to record and save the echo presentation as a video file. Each screen recording you make is saved in .mp4 format on the Processor Unit hard disk. The file name reflects the current date and time.

Select **Screen Recording** to start and stop the recording from the Operating Panel.

Use the **Screen Recording** page to define where the video files are saved. This page is located in the **Output** dialog box.

Delete Oldest Marker


The CS90 system offers several different marker types. You can add as many markers as you like. The most common markers can be added using dedicated buttons on the Operating Panel. Other markers are added using the shortcut menu in each view. Each marker is identified with its geographical location.

Select **Delete Oldest Marker** to use the Operating Panel to remove the oldest marker from the echo presentation.

Send to External

Each marker is identified with its geographical location. This marker location can be very useful for other instruments. For example, you can export this information to a chart plotter. You can configure your CS90 system to export marker information. You must choose a suitable output port and select which datagram formats to export.

Tip

 Use the **Output Marker** page to export target markers to a communication port. This page is located in the **Output** dialog box. To open, select it on the **Operation** menu.

Place the cursor on the marker from which you want to export the target information. Press **Send To External**.

Place Marker

Press **Place Marker** to create a visual marker symbol at the cursor's current position. Each marker is shown as a small triangle with or without a short identifying label.


In this context, the phrase *marker* is used to identify a visual symbol placed in the display presentation. A marker is thus a graphical indicator used to identify and highlight specific locations or objects. You can use markers to pinpoint and label interesting positions, objects or targets the CS90 system detects. Placing a marker on an echo identifies the echo as "interesting". It is regarded as an *object* that you can act upon.

Delete All Objects

Placing a marker on an echo identifies the echo as "interesting". It is regarded as an *object* that you can act upon. You can add as many markers as you like.

Markers are shown as small triangles. Select **Delete All Objects** to remove all the markers from the views.

Tip

 You can delete a single marker, or multiple markers simultaneously, by selecting **Delete** in the **Objects** menu. You can also use the shortcut menu to delete markers. If you use **Delete Marker** on the shortcut menu you can only remove one marker at a time.

Increase Display Gain / Decrease Display Gain

Use **Display Gain** to increase or decrease the "strength" of the echo presentation.

Use this setting together with **Gain** to adjust the sensitivity of the CS90 system. **Display Gain** controls the "amount" of echo that is displayed, in other words the "strength" or "intensity" of the echo presentation. The function thus increases or decreases the presentation of the echo colours.

Adjust the **Display Gain** so that you can see the targets without too much noise and reverberation. The chosen setting is a matter of personal preferences.

Tip



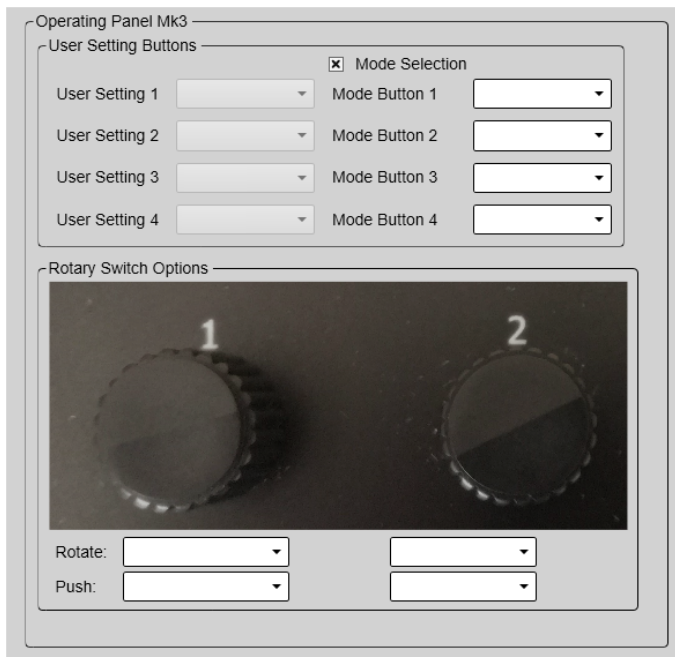
Open this function from the **Display** menu.

Joystick Options

Use these settings to set up the joystick operation.

Operating Panel Mk3

The Mk3 Operating Panel is connected to the Processor Unit with a USB cable. A dedicated power supply unit is not required.



Details

User Settings / Presentation Modes

On the Mk3 Operating Panel, the requested user setting or presentation mode is chosen with a single button. Press the button repeatedly to cycle through the settings or modes. Select **Mode Selection** to specify what you want to use the button for.



Tip



Before you can assign custom user settings to the operating panel, a selection of settings must be available from the **User Settings** dialog box. The **User Settings** dialog box is located on the **Main** menu.

Any user setting selected on the Operating Panel is identified in the upper left corner of the Horizontal view. The identifying number refers to the **User Setting** number on the **Operating Panel** page. Click on the text to make it larger. Click one more time to restore the original font size.

Rotary Switch Functions (Rotate)

The Mk3 Operating Panel is fitted with two rotary switches. The switches are identified with numbers. Each switch can be assigned a function related to range, gain, bearing or tilt.

Under **Rotary Switch Options**, assign one **Rotate** function to each rotary switch on the Operating Panel. The following functions can be assigned:

Horizontal Range

This is the range setting in the *Horizontal* view.

Horizontal Range 2

This is the range setting in the *second Horizontal* view when a "dual" presentation mode is used.

Horizontal Range 3

This is the range setting in the *third Horizontal* view when the *QuadPing™* presentation mode is used.

Vertical Range

This is the range setting in the *Vertical* view.

Vertical Range 2

This is the range setting in the *second Vertical* view when a "dual" presentation mode is used.

Inspection Range

This is the range setting in the *Inspection* view.

Plane Range

This is the range setting in the *Plane* view.

Active Ping Range

This is the range setting in the currently active view.

Active Ping Gain

This is the gain setting in the currently active view

Active Ping Bearing

This is the bearing setting in the currently active view.

Active Ping Tilt

This is the tilt setting in the currently active view

Display Gain

Use this setting together with **Gain** to adjust the sensitivity of the CS90 system. **Display Gain** controls the "amount" of echo that is displayed, in other words the "strength" or "intensity" of the echo presentation. The function thus increases or decreases the presentation of the echo colours.

The gain is increased and decreased in steps of 1 dB. The chosen display gain will automatically apply to all the beams.

You can also control this functionality from the **Display** menu.

Rotary Switch Functions (Push)

Assign one **Push** function to each rotary switch. The assigned function is activated when you *press* the rotary switch.

None

No specific functionality is assigned.

Auto Tilt

This is an "on/off" function. When *Auto Tilt* mode is activated the beam will automatically change its tilt angle for each transmission ("ping"). The centre of the tilt sector is defined by the chosen tilt angle just before the *Auto Tilt* mode is started. The chosen tilt sector is shown on the tilt indicator in the *Horizontal* view using a shaded background. The sector and step settings are made using the **Tilt** function on the **Main** menu.

Zoom

Place the cursor anywhere in the view, right-click and select **Zoom**. Only one zoom level is provided. Select **Zoom** one more time to restore the original view.

Menu Off

This is an "on/off" function. Unless you need to make frequent changes to the operating parameters, you may want to hide the menu from the display presentation. This gives you more space for echo information.

Own Ship

This is the same function as **Place Own Ship Marker** on the shortcut menu. Select this function to add a square symbol to the vessel's current position in the echo presentation. The own ship marker is now regarded as an *object*. All information

about the object is shown in the **Objects** menu listed as "OSM". Use **Delete Own Ship Marker** on the shortcut menu to delete the marker from the current view.

Auto Bearing

This is an "on/off" function. Set this function to *On* to start the automatic search function. In the *Auto Bearing* mode the CS90 system will automatically search within defined sector limits. The sector is identified in the view using two angular symbols. The sector and step settings are made using the **Bearing** function on the **Main** menu.

Screen Recording

This is an "on/off" function. The **Screen Recording** function allows you to record and save the echo presentation as a video file. Each screen recording you make is saved in .mp4 format on the Processor Unit hard disk. The file name reflects the current date and time.

Select **Screen Recording** to start and stop the recording from the Operating Panel.

Use the **Screen Recording** page to define where the video files are saved. This page is located in the **Output** dialog box.

Delete Oldest Marker

The CS90 system offers several different marker types. You can add as many markers as you like. The most common markers can be added using dedicated buttons on the Operating Panel. Other markers are added using the shortcut menu in each view. Each marker is identified with its geographical location.

Select **Delete Oldest Marker** to use the Operating Panel to remove the oldest marker from the echo presentation.

Send to External

Each marker is identified with its geographical location. This marker location can be very useful for other instruments. For example, you can export this information to a chart plotter. You can configure your CS90 system to export marker information. You must choose a suitable output port and select which datagram formats to export.

Tip



*Use the **Output Marker** page to export target markers to a communication port. This page is located in the **Output** dialog box. To open, select it on the **Operation** menu.*

Place the cursor on the marker from which you want to export the target information. Press **Send To External**.

Place Marker

Press **Place Marker** to create a visual marker symbol at the cursor's current position. Each marker is shown as a small triangle with or without a short identifying label.

In this context, the phrase *marker* is used to identify a visual symbol placed in the display presentation. A marker is thus a graphical indicator used to identify and highlight specific locations or objects. You can use markers to pinpoint and label interesting positions, objects or targets the CS90 system detects. Placing a marker on an echo identifies the echo as "interesting". It is regarded as an *object* that you can act upon.

Delete All Objects

Placing a marker on an echo identifies the echo as "interesting". It is regarded as an *object* that you can act upon. You can add as many markers as you like.

Markers are shown as small triangles. Select **Delete All Objects** to remove all the markers from the views.

Tip



*You can delete a single marker, or multiple markers simultaneously, by selecting **Delete** in the **Objects** menu. You can also use the shortcut menu to delete markers. If you use **Delete Marker** on the shortcut menu you can only remove one marker at a time.*

Increase Display Gain / Decrease Display Gain

Use **Display Gain** to increase or decrease the "strength" of the echo presentation.

Use this setting together with **Gain** to adjust the sensitivity of the CS90 system. **Display Gain** controls the "amount" of echo that is displayed, in other words the "strength" or "intensity" of the echo presentation. The function thus increases or decreases the presentation of the echo colours.

Adjust the **Display Gain** so that you can see the targets without too much noise and reverberation. The chosen setting is a matter of personal preferences.

Tip



*Open this function from the **Display** menu.*

Computer audio enabled for transducer movements

The Operating Panel is not fitted with a loudspeaker. Select this function to allow the Processor Unit to provide audio notifications when you lower or hoist the transducer.

Minimum display requirements

You can use more than one display on your Processor Unit depending on personal and/or operational preferences.

Note



Make sure that the chosen display meets the requirements for the CS90 system. The design and construction must allow for marine use, and the display must be able to withstand the movements and vibrations normally experienced on a vessel. Verify that you have easy access to cables and connectors, and that the display can be installed in a safe and secure way.

The minimum technical requirements for the display are:

Resolution

Minimum requirement: 1280 x 1024 pixels

The visual quality of the presentation depends on the quality of your graphic adapter and display. We recommend that you use a large display with resolution 1920 x 1080 or 1920 x 1200.

Video interface

The video interface must match the output format(s) provided by the Processor Unit. The Processor Unit may offer video output on several formats. Investigate your options before you purchase a display.

Physical screen size

The screen size depends on personal and/or operational preferences. We recommend that you use 24 inch or bigger diagonal screen size. The CS90 software supports 16:9 and 16:10 displays.

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